

Chapter	Contents	Page No
1	Introduction	1
	1.1. Gas Metal Arc Welding (GMAW)	1
	1.2. Welding Automation	3
	1.3. Welding Safety	3
2	Design of Robot	4
	2.1. Kinematics of Robot	4
	2.2. Design Approach	7
	2.3. Welding Installation and Procedures	24
3	Robot Installation and Procedures	26
	3.1. Control System	26
	3.2. Motion Controller Architecture	27
	3.3. Designed Specification of Robot	29
	3.4. Degrees of Freedom of Arc Welding Robot	30
4	Parts List	31
5	Technical Description of Robot	66
	5.1. Brief Description	66
	5.2. Four-axis Arc Welding Robot	66
	5.3. Axes of Robot	67
	5.4. Specifications	67
6	System Wise Assembly & Component Drawings, Item List and Standard Part Description	68
7	Robot Operating Procedures	92
	7.1. Safety Notice	92
	7.2. Four Axis Arc Welding Robot	93
	7.3. Important Components	94
	7.4. Example Program	100
8	Robot Installation Procedures	103
	8.1. Design Specification of Robot	103
	8.2. Main Power On/Off Switch	103
	8.3. Important Components	103
	8.4. PLC Control System	104
	8.5. Installation Procedure	105
	8.6. Block Diagram	105

9	Teach-in Mode Program	114
	9.1. Remote Pendant	114
	9.2. Joystick - 1	114
	9.3. Joystick - 2	115
	9.4. Home	115
	9.5. Teach	116
	9.6. Start	116
	9.7. Stop	116
	9.8. Example Program	116
	9.9. Procedure	117
	9.10. Flow Chart	118
10	References	119